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**Geometry of the Shilov boundary of bounded symmetric
domains**

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I Hermitian symmetric spaces

I.1 Riemannian symmetric space

A (connected) Riemannian manifold (M, g) is a *Riemannian symmetric space* if,

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The group $Is(M)$ of isometries of M , with the compact-open topology is a Lie group (Myers-Steenrod). By composing symmetries, the group $Is(M)$ is easily shown to be *transitive* on M . Let G be the neutral component of $Is(M)$. Then G is already transitive on M .

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Fix an origin o in M , and let K be the isotropy subgroup of o in G . Then K is a closed compact subgroup of G , and $M \simeq G/K$.

Let \mathfrak{g} be the Lie algebra of G , and \mathfrak{k} the Lie algebra of K . The tangent space T_oM of M at o can be identified with $\mathfrak{g}/\mathfrak{k}$.

The map

$$\theta : G \longrightarrow G, \quad g \longmapsto s_0 \circ g \circ s_0$$

is an involutive isomorphism of G . Let $G^\theta = \{g \in G, \theta(g) = g\}$.

Then

$$(G^\theta)_o \subset K \subset G^\theta.$$

The differential of θ at the identity is a Lie algebra involution of \mathfrak{g} , still denoted by θ and yields a decomposition

$$\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$$

$$\mathfrak{k} = \{X \in \mathfrak{g}, \theta X = X\}, \mathfrak{p} = \{X \in \mathfrak{g}, \theta X = -X\}.$$

Moreover

$$[\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k}, \quad [\mathfrak{k}, \mathfrak{p}] \subset \mathfrak{p}, \quad [\mathfrak{p}, \mathfrak{p}] \subset \mathfrak{k} .$$

The projection from \mathfrak{g} to \mathfrak{k} along \mathfrak{k} yields an isomorphism of $\mathfrak{g}/\mathfrak{k}$ with \mathfrak{p} , and hence there is a natural identification $T_oM \simeq \mathfrak{p}$.

Proposition 1. *Let X be in \mathfrak{p} . Let $g_t = \exp tX$ be the one-parameter group of G generated by X . Then $\gamma_X(t) = g_t(o)$ is the geodesic emanating from o with tangent vector X at o . Moreover*

$$g_t = s_{\gamma_X(\frac{t}{2})} \circ s_0 .$$

The vector space \mathfrak{p} is naturally equipped with a *Lie triple product* (LTS) , defined by

$$[X, Y, Z] = [[X, Y], Z].$$

Proposition 2. *The Lie triple product on \mathfrak{p} satisfies the following identities*

$$[X, Y, Z] = -[Y, X, Z]$$

$$[X, Y, Z] + [Y, Z, X] + [Z, X, Y] = 0$$

$$[U, V, [X, Y, Z]] = [[U, V, X], Y, Z] + [X, [U, V, Y], Z] + [X, Y, [U, V, Z]]$$

This Lie triple product has a nice geometric interpretation, namely

$$R_o(X, Y)Z = -[[X, Y], Z] = -[X, Y, Z]$$

where R_o is the *curvature tensor* of M at o ,

The *Ricci curvature* at o (also called the Ricci form) is the symmetric bilinear form on T_oM given by

$$r_o(X, Y) = -\mathbf{tr}(Z \longmapsto R_o(X, Z)Y) .$$

Proposition 3. *The Ricci curvature at o satisfies*

$$r_o(X, Y) = -\frac{1}{2}B(X, Y)$$

where $B(X, Y) = \text{tr}_{\mathfrak{g}}(\text{ad } X \text{ ad } Y)$ is the Killing form of the Lie algebra \mathfrak{g} .

A Riemannian symmetric space $M \simeq G/K$ is said to be *irreducible* if the representation of K on the tangent space $T_oM \simeq \mathfrak{p}$ is irreducible (i.e. admits no invariant subspaces except $\{0\}$ and \mathfrak{p}).

If M is irreducible, then there exists a unique (up to a positive real constant) K -invariant inner product on \mathfrak{p} , and the Ricci form r_o has to be proportional to it.

An irreducible Riemannian symmetric space is said to be

of the Euclidean type if r_o is identically 0

of the compact type if r_o is positive definite

of the noncompact type if r_o is negative definite

Any simply connected Riemannian symmetric space M is a product of irreducible Riemannian symmetric spaces. If all factors are of the compact (resp. noncompact, Euclidean) type, then M is said to be of the compact (resp. noncompact, Euclidean) type.

If M is of compact type, then G is a compact semisimple Lie group, and if M is of the noncompact type, then G is a semisimple Lie group (with no compact factors) and θ is a Cartan involution of G .

For the Riemannian symmetric spaces of the noncompact type, the infinitesimal data characterize the space. More precisely, given a semisimple Lie algebra \mathfrak{g} (with no compact factors), let G be any connected Lie group with Lie algebra \mathfrak{g} and with finite center (there always exist such groups). Let θ be a Cartan involution of \mathfrak{g} (there is hardly any choice, as two Cartan involutions of \mathfrak{g} are conjugate under the adjoint action of G on \mathfrak{g}). Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be the corresponding Cartan decomposition of \mathfrak{g} . The Killing form B of \mathfrak{g} is negative definite on \mathfrak{k} and positive-definite on \mathfrak{p} . The involution θ can be lifted to an involutive automorphism of G , still denoted by θ . Then $K = G^\theta$ is a compact connected subgroup of G . Let $X = G/K$, and set $o = eK$. Then the tangent space at o is naturally isomorphic to \mathfrak{p} and $B|_{\mathfrak{p} \times \mathfrak{p}}$ is a K -invariant inner product on \mathfrak{p} .

Hence X can be equipped with a (unique) structure of Riemannian manifold, on which G acts by isometries. The space X does not depend on the choice of G (up to isomorphism), but only on \mathfrak{g} .

I.2 Hermitian symmetric spaces

Let M be a complex (connected) manifold with a Hermitian structure. M is said to be a *Hermitian symmetric space* if for each point m in M there exists an involutive *holomorphic* isometry s_m of M such that m is an isolated fixed point of s_m .

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There are special cases of Riemannian symmetric spaces, but we demand that the symmetries be holomorphic. As G (the neutral component of $Is(M)$) is generated by even products of symmetries, then G acts by holomorphic transformations on M . [One should however observe that G is *not* a complex Lie group].

Use same notation as before. In particular \mathfrak{p} being isomorphic to the tangent space T_oM , admits a complex structure, i.e. a (\mathbb{R} -linear operator) $J = J_o$ which satisfies $J^2 = -\text{id}$.

Proposition 4. *The complex structure operator J satisfies*

$$J([T, X]) = [T, JX], \text{ for all } T \in \mathfrak{k}, X \in \mathfrak{p}$$

$$B(JX, JY) = B(X, Y), \text{ for all } X, Y \in \mathfrak{p}$$

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Proposition 5. *There exists a unique element H in the center of \mathfrak{k} such that $J = \text{ad}_{\mathfrak{p}} H$.*

Proposition 6. *Let \mathfrak{g} be a simple Lie algebra of the noncompact type, with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$. The associated Riemannian symmetric space $M \simeq G/K$ is a Hermitian symmetric space if and only if the center of \mathfrak{k} is $\neq \{0\}$. Then there exists a unique (up to ± 1) element H in the center of \mathfrak{k} such that $\text{ad } H$ induces a complex structure operator on \mathfrak{p} and G/K is, in a natural way a Hermitian symmetric space of the noncompact type.*

I.3 Jordan triple system

Let $M \simeq G/K$ be a Hermitian symmetric of the noncompact type. Then $\mathfrak{p} \simeq T_oM$ is equipped with its natural structure of Lie triple system, which coincides with the curvature tensor at o . The behaviour of the curvature tensor under the action of J the complex structure at o is rather intricate. It leads to the following definition.

Let, for X, Y, Z in \mathfrak{p}

$$\{X, Y, Z\} = \frac{1}{2}([\![X, Y]\!]Z + J[\![X, JY]\!]Z)$$

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$$\{X, Y, Z\} = \frac{1}{2}([\![X, Y]\!, Z] + J[\![X, JY]\!, Z])$$

Theorem 7. *The triple product defined by the formula above satisfies the following identities, for X, Y, Z, U, V in \mathfrak{p} :*

$$(JT1) \quad J\{X, Y, Z\} = \{JX, Y, Z\} = -\{X, JY, Z\} = \{X, Y, JZ\}$$

$$(JT2) \quad \{X, Y, Z\} = \{Z, Y, X\}$$

(JT3)

$$\{U, V \{X, Y, Z\}\} = \{\{U, V, X\}, Y, Z\} - \{X, \{V, U, Y\}, Z\} + \{X, Y, \{U, V, Z\}\}$$

Moreover, it satisfies

$$[[X, Y], Z] = \{X, Y, Z\} - \{Y, X, Z\} .$$

A complex vector space \mathbb{V} together with a triple product $\{X, Y, Z\}$ which is \mathbb{C} -linear in X and Z , conjugate linear in Y , and satisfy $(JT2)$ and $(JT3)$ is called a (complex) *Jordan triple system*.

Let $L(X, Y)$ be the (\mathbb{C} -linear) operator on \mathbb{V} defined by $L(X, Y)Z = \{X, Y, Z\}$, and consider the sesquilinear form

$$\tau(X, Y) = \mathbf{tr} L(X, Y)$$

If the form τ is nondegenerate, then τ is Hermitian ($\tau(X, Y) = \overline{\tau(Y, X)}$). The triple is said to be a *positive Hermitian Jordan triple system* (PHJTS) if the form τ is positive definite.

Theorem 8. *Let $M \simeq G/K$ be a Hermitian symmetric space of the noncompact type. Then (\mathfrak{p}, J) (considered as a complex vector space) with its natural Jordan triple product is a PHJTS.*

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Summary

Riemannian symmetric spaces of the NC type \equiv LTS with negative Ricci form

Hermitian symmetric spaces of the NC type \equiv PHJTS

This correspondances can be extended to morphisms.