

A Recursion Operator for the Geodesic Flow on n -dimensional Sphere

Kiyonori HOSOKAWA

Ph.D. student, the Prof. Yoshioka Laboratory,
Department of Mathematics, Graduate School of Science,
Tokyo University of Science

Varna,
Bulgaria,
June 7th - 12th,
2013

Outline

Outline

1 Preface

Outline

- 1 Preface
- 2 Definition

Outline

- 1 Preface
- 2 Definition
- 3 Introduction of the recursion operator

Outline

- 1 Preface
- 2 Definition
- 3 Introduction of the recursion operator
- 4 Construction of a recursion operator for the geodesic flow on n -dimensional sphere

Outline

- 1 Preface
- 2 Definition
- 3 Introduction of the recursion operator
- 4 Construction of a recursion operator for the geodesic flow on n -dimensional sphere
- 5 Application of a recursion operator for the geodesic flow on n -dimensional sphere

Outline

- 1 Preface
- 2 Definition
- 3 Introduction of the recursion operator
- 4 Construction of a recursion operator for the geodesic flow on n -dimensional sphere
- 5 Application of a recursion operator for the geodesic flow on n -dimensional sphere
- 6 Conclusion

1. Preface

1. Preface - 1

- For a completely integrable system, the way of finding the first integrals is not formulated in general.

1. Preface - 1

- For a completely integrable system, the way of finding the first integrals is not formulated in general.
- Liouville proved that a system with n degrees of freedom is integrable by quadratures when there exist n independent first integrals in involution (cf. [1]).

1. Preface - 1

- For a completely integrable system, the way of finding the first integrals is not formulated in general.
- Liouville proved that a system with n degrees of freedom is integrable by quadratures when there exist n independent first integrals in involution (cf. [1]).
- In classical mechanics, *a completely integrable system* in the sense of Liouville are called simply *an integrable system*.

1. Preface - 2

- Also, integrable systems were characterized by [2], [3], [4] and [5] papers related to the recursion operator since 1980 have been written ([5]).

1. Preface - 2

- Also, integrable systems were characterized by [2], [3], [4] and [5] papers related to the recursion operator since 1980 have been written ([5]).
- The integrable system is characterized by the recursion operator T in the Hamiltonian dynamical system on the cotangent vector bundle $T^*\mathcal{M}$ of a manifold \mathcal{M} .

1. Preface - 2

- Also, integrable systems were characterized by [2], [3], [4] and [5] papers related to the recursion operator since 1980 have been written ([5]).
- The integrable system is characterized by the recursion operator T in the Hamiltonian dynamical system on the cotangent vector bundle $T^*\mathcal{M}$ of a manifold \mathcal{M} . T is a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field which satisfies certain conditions. In particular, the recursion operator is written in the following form if we choose an action-angle variables (J_k, φ^k) :

1. Preface - 2

- Also, integrable systems were characterized by [2], [3], [4] and [5] papers related to the recursion operator since 1980 have been written ([5]).
- The integrable system is characterized by the recursion operator T in the Hamiltonian dynamical system on the cotangent vector bundle $T^*\mathcal{M}$ of a manifold \mathcal{M} . T is a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field which satisfies certain conditions. In particular, the recursion operator is written in the following form if we choose an action-angle variables $(\mathbf{J}_k, \varphi^k)$:

$$T = \sum_k \lambda^k(\mathbf{J}_k) \left(\frac{\partial}{\partial \mathbf{J}_k} \otimes d\mathbf{J}_k + \frac{\partial}{\partial \varphi^k} \otimes d\varphi^k \right),^{(*)}$$

where $\lambda^k(\mathbf{J}_k)$ is doubly degenerate eigenvalues.

1. Preface - 2

- Also, integrable systems were characterized by [2], [3], [4] and [5] papers related to the recursion operator since 1980 have been written ([5]).
- The integrable system is characterized by the recursion operator T in the Hamiltonian dynamical system on the cotangent vector bundle $T^*\mathcal{M}$ of a manifold \mathcal{M} . T is a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field which satisfies certain conditions. In particular, the recursion operator is written in the following form if we choose an action-angle variables $(\mathbf{J}_k, \varphi^k)$:

$$T = \sum_k \lambda^k(\mathbf{J}_k) \left(\frac{\partial}{\partial \mathbf{J}_k} \otimes d\mathbf{J}_k + \frac{\partial}{\partial \varphi^k} \otimes d\varphi^k \right),^{(*)}$$

where $\lambda^k(\mathbf{J}_k)$ is doubly degenerate eigenvalues.

- Functionally independent constants of the motion are obtained by taking each trace of T^k :

$$Tr(T^k), \quad (k = 1, 2, \dots, n).$$

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.
- Now, we consider about a recursion operator from the viewpoint of geometry, specifically for the geodesic flow on n -dimensional sphere S^n case.

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.
- Now, we consider about a recursion operator from the viewpoint of geometry, specifically for the geodesic flow on n -dimensional sphere S^n case.

The purpose of this talk is:

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.
- Now, we consider about a recursion operator from the viewpoint of geometry, specifically for the geodesic flow on n -dimensional sphere S^n case.

The purpose of this talk is:

- Introducing the recursion operator for the geodesic flow on S^n that we had obtained,

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.
- Now, we consider about a recursion operator from the viewpoint of geometry, specifically for the geodesic flow on n -dimensional sphere S^n case.

The purpose of this talk is:

- Introducing the recursion operator for the geodesic flow on S^n that we had obtained,
- Giving an application of the recursion operator for the geodesic flow on S^n ;

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.
- Now, we consider about a recursion operator from the viewpoint of geometry, specifically for the geodesic flow on n -dimensional sphere S^n case.

The purpose of this talk is:

- Introducing the recursion operator for the geodesic flow on S^n that we had obtained,
- Giving an application of the recursion operator for the geodesic flow on S^n ; we obtain
 - *a sequence of Abelian symmetries between Hamiltonian vector fields,*

1. Preface - 3

- There are some examples about constructing recursion operators from the viewpoint of physics; 1-dimensional harmonic oscillator, Kepler problem, KdV equation, etc.
- Now, we consider about a recursion operator from the viewpoint of geometry, specifically for the geodesic flow on n -dimensional sphere S^n case.

The purpose of this talk is:

- Introducing the recursion operator for the geodesic flow on S^n that we had obtained,
- Giving an application of the recursion operator for the geodesic flow on S^n ;
we obtain
 - a sequence of Abelian symmetries between Hamiltonian vector fields,
 - a sequence of involutive Hamiltonian functions,

2. Definition

2. Definition - 1

We introduce endomorphisms \hat{T} and \check{T} induced by a $(\mathbf{1}, \mathbf{1})$ -tensor T given in [5]:

2. Definition - 1

We introduce endomorphisms \hat{T} and \check{T} induced by a $(\mathbf{1}, \mathbf{1})$ -tensor T given in [5]:

Definition (Endomorphisms)

Let T be a $(\mathbf{1}, \mathbf{1})$ -tensor field on a manifold \mathcal{M} and we write $T : (\mathbf{1}, \mathbf{1})$ -tensor *s.t.*

$$T = \sum_{i,j=1}^n T_i^j dx^i \otimes \frac{\partial}{\partial x^j}.$$

2. Definition - 1

We introduce endomorphisms \hat{T} and \check{T} induced by a $(\mathbf{1}, \mathbf{1})$ -tensor T given in [5]:

Definition (Endomorphisms)

Let T be a $(\mathbf{1}, \mathbf{1})$ -tensor field on a manifold \mathcal{M} and we write $T : (\mathbf{1}, \mathbf{1})$ -tensor *s.t.*

$$T = \sum_{i,j=1}^n T_i^j dx^i \otimes \frac{\partial}{\partial x^j}.$$

Then we define endomorphisms \hat{T} and \check{T} by:

$$\begin{aligned} \hat{T} : T_p \mathcal{M} \ni X \mapsto \hat{T}X \in T_p \mathcal{M}, \quad \hat{T}X &= \sum_{i,j=1}^n T_i^j X^i \frac{\partial}{\partial x^j}, \\ \check{T} : T_p^* \mathcal{M} \ni \alpha \mapsto \check{T}\alpha \in T_p^* \mathcal{M}, \quad \check{T}\alpha &= \sum_{i,j=1}^n \alpha_j T_i^j dx^i, \end{aligned}$$

where a vector field X and a 1-form α *s.t.*

$$X = \sum_{k=1}^n X^k \frac{\partial}{\partial x^k}, \quad \alpha = \sum_{k=1}^n \alpha_k dx^k.$$

2. Definition - 2

And, we introduce a separability of a dynamical vector field ([5]):

2. Definition - 2

And, we introduce a separability of a dynamical vector field ([5]):

Definition (Separability)

A dynamical vector field Δ is said to be *separable on an open subset* $O \subseteq M$ when there exists a basis $\{e_i\}$ of local vector fields on O *s.t.*

$$\mathcal{L}_{e_i} \langle \Delta, \vartheta^j \rangle \neq 0 \Rightarrow i = j,$$

where $\{\vartheta^j\}$ is the dual basis of $\{e_i\}$.

2. Definition - 2

And, we introduce a separability of a dynamical vector field ([5]):

Definition (Separability)

A dynamical vector field Δ is said to be *separable on an open subset* $O \subseteq \mathcal{M}$ when there exists a basis $\{e_i\}$ of local vector fields on O *s.t.*

$$\mathcal{L}_{e_i} \langle \Delta, \vartheta^j \rangle \neq 0 \Rightarrow i = j,$$

where $\{\vartheta^j\}$ is the dual basis of $\{e_i\}$. If $O = \mathcal{M}$, we call Δ is separable.

3. Introduction of the recursion operator

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

Theorem (DMSV[5])

Let a vector field Δ is a dynamical vector field on a $2n$ -dimensional manifold \mathcal{M} and suppose Δ admits a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field T *s.t.*

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

Theorem (DMSV[5])

Let a vector field Δ is a dynamical vector field on a $2n$ -dimensional manifold \mathcal{M} and suppose Δ admits a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field T s.t.

- 1 T is invariant under Δ : $\mathcal{L}_\Delta T = 0$,

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

Theorem (DMSV[5])

Let a vector field Δ is a dynamical vector field on a $2n$ -dimensional manifold \mathcal{M} and suppose Δ admits a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field T s.t.

- 1 T is invariant under Δ : $\mathcal{L}_\Delta T = \mathbf{0}$,
- 2 T has vanishing Nijenhuis torsion : $\mathcal{N}_T = \mathbf{0}$,

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

Theorem (DMSV[5])

Let a vector field Δ is a dynamical vector field on a $2n$ -dimensional manifold \mathcal{M} and suppose Δ admits a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field T s.t.

- 1 T is invariant under Δ : $\mathcal{L}_\Delta T = \mathbf{0}$,
- 2 T has vanishing Nijenhuis torsion : $\mathcal{N}_T = \mathbf{0}$,
- 3 T has doubly degenerate eigenvalues λ^j with nowhere vanishing differentials :
 $\text{deg } \lambda^j = 2, \quad (d\lambda^j)_p \neq \mathbf{0}, \quad \forall p \in \mathcal{M}, \quad (j = 1, \dots, n).$

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

Theorem (DMSV[5])

Let a vector field Δ is a dynamical vector field on a $2n$ -dimensional manifold \mathcal{M} and suppose Δ admits a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field T s.t.

- 1 T is invariant under Δ : $\mathcal{L}_\Delta T = 0$,
- 2 T has vanishing Nijenhuis torsion : $\mathcal{N}_T = 0$,
- 3 T has doubly degenerate eigenvalues λ^j with nowhere vanishing differentials :
 $\text{deg } \lambda^j = 2, \quad (d\lambda^j)_p \neq 0, \quad \forall p \in \mathcal{M}, \quad (j = 1, \dots, n).$

Then, the vector field Δ is separable, completely integrable and Hamiltonian with respect to a certain symplectic structure.

3. Introduction of the recursion operator - 1

We describe a new characterization of integrable systems. Specifically, we consider a diagonalizable tensor.

Theorem (DMSV[5])

Let a vector field Δ is a dynamical vector field on a $2n$ -dimensional manifold \mathcal{M} and suppose Δ admits a diagonalizable $(\mathbf{1}, \mathbf{1})$ -tensor field T s.t.

- 1 T is invariant under Δ : $\mathcal{L}_\Delta T = 0$,
- 2 T has vanishing Nijenhuis torsion : $\mathcal{N}_T = 0$,
- 3 T has doubly degenerate eigenvalues λ^j with nowhere vanishing differentials :
 $\deg \lambda^j = 2, \quad (d\lambda^j)_p \neq 0, \quad \forall p \in \mathcal{M}, \quad (j = 1, \dots, n)$.

Then, the vector field Δ is separable, completely integrable and Hamiltonian with respect to a certain symplectic structure.

This T is called a recursion operator of the vector field Δ .

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

When $(\mathbf{1}, \mathbf{1})$ -tensor T is a recursion operator in finite dimensional case, we get:

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

When $(\mathbf{1}, \mathbf{1})$ -tensor T is a recursion operator in finite dimensional case, we get:

- There exist n vector fields Δ_k s.t.

$$\Delta_{k+1} = \hat{T}\Delta_k, \quad (k \geq 1).$$

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

When $(\mathbf{1}, \mathbf{1})$ -tensor T is a recursion operator in finite dimensional case, we get:

- There exist n vector fields Δ_k s.t.

$$\Delta_{k+1} = \hat{T}\Delta_k, \quad (k \geq 1).$$

- There exist n differential 1-form s.t.

$$(d\alpha = 0, d\check{T}\alpha = 0, \mathcal{L}_T = 0) \Rightarrow d(\check{T}^n\alpha) = 0, \quad (k \geq 1).$$

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

When $(\mathbf{1}, \mathbf{1})$ -tensor T is a recursion operator in finite dimensional case, we get:

- There exist n vector fields Δ_k s.t.

$$\Delta_{k+1} = \hat{T}\Delta_k, \quad (k \geq 1).$$

- There exist n differential 1-form s.t.

$$(d\alpha = 0, d\check{T}\alpha = 0, \mathcal{L}_T = 0) \Rightarrow d(\check{T}^n\alpha) = 0, \quad (k \geq 1).$$

- Under the flow generated by a vector field Δ , the invariance of T implies the invariance of $\hat{T}\Delta_n$, $\check{T}^n\alpha$ and its eigenvalues λ .

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

When $(\mathbf{1}, \mathbf{1})$ -tensor T is a recursion operator in finite dimensional case, we get:

- There exist n vector fields Δ_k s.t.

$$\Delta_{k+1} = \hat{T}\Delta_k, \quad (k \geq 1).$$

- There exist n differential 1-form s.t.

$$(d\alpha = 0, d\check{T}\alpha = 0, \mathcal{L}_T = 0) \Rightarrow d(\check{T}^n\alpha) = 0, \quad (k \geq 1).$$

- Under the flow generated by a vector field Δ , the invariance of T implies the invariance of $\hat{T}\Delta_n$, $\check{T}^n\alpha$ and its eigenvalues λ .
- About the Hamiltonian H and the symplectic structure ω for the system, the all of Δ_k is Hamiltonian vector field when

$$i_{\Delta}\omega = -dH.$$

3. Introduction of the recursion operator - 2

The properties of Recursion operator T :

When $(\mathbf{1}, \mathbf{1})$ -tensor T is a recursion operator in finite dimensional case, we get:

- There exist n vector fields Δ_k s.t.

$$\Delta_{k+1} = \hat{T}\Delta_k, \quad (k \geq 1).$$

- There exist n differential 1-form s.t.

$$(d\alpha = 0, d\check{T}\alpha = 0, \mathcal{L}_T = 0) \Rightarrow d(\check{T}^n\alpha) = 0, \quad (k \geq 1).$$

- Under the flow generated by a vector field Δ , the invariance of T implies the invariance of $\hat{T}\Delta_n$, $\check{T}^n\alpha$ and its eigenvalues λ .
- About the Hamiltonian H and the symplectic structure ω for the system, the all of Δ_k is Hamiltonian vector field when

$$i_{\Delta}\omega = -dH.$$

- Trace of T^k is the constants of motion of the system:

$$Tr(T^k), \quad (k \geq 1).$$

4. Construction of a recursion operator for the geodesic flow on n -dimensional sphere

4. Construction of a recursion op. for the geodesic flow on S^n - 1

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

4. Construction of a recursion op. for the geodesic flow on S^n - 1

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

The process is:

4. Construction of a recursion op. for the geodesic flow on S^n - 1

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

The process is:

- 1 Considering the canonical Riemannian metric on S^n .

4. Construction of a recursion op. for the geodesic flow on S^n - 1

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

The process is:

- ① Considering the canonical Riemannian metric on S^n .
- ② Calculating the Hamiltonian H from the metric.

4. Construction of a recursion op. for the geodesic flow on S^n - 1

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

The process is:

- 1 Considering the canonical Riemannian metric on S^n .
- 2 Calculating the Hamiltonian H from the metric.
- 3 Describing the Hamiltonian system (H, Δ, ω) by the action-angle variables (J_k, φ^k) .

4. Construction of a recursion op. for the geodesic flow on S^n - 1

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

The process is:

- ① Considering the canonical Riemannian metric on S^n .
- ② Calculating the Hamiltonian H from the metric.
- ③ Describing the Hamiltonian system (H, Δ, ω) by the action-angle variables (J_k, φ^k) .

then we get a recursion operator T .

4. Construction of a recursion op. for the geodesic flow on $S^n - 1$

We had obtained a recursion operator of n -dimensional sphere S^n on our last research paper.

The process is:

- 1 Considering the canonical Riemannian metric on S^n .
- 2 Calculating the Hamiltonian H from the metric.
- 3 Describing the Hamiltonian system (H, Δ, ω) by the action-angle variables (J_k, φ^k) .

then we get a recursion operator T .

And, the constants of motion is written by the trace of T^k :

$$\{Tr(T), Tr(T^2), \dots, Tr(T^n)\}.$$

4. Construction of a recursion op. for the geodesic flow on S^n - 2

- ① Considering the canonical Riemannian metric on S^n

4. Construction of a recursion op. for the geodesic flow on $S^n - 2$

① Considering the canonical Riemannian metric on S^n

Using the spherical polar coordinate for an n -dimensional sphere of radius a , we consider an embedding ϕ to the sphere:

$$\phi(q^1, \dots, q^n) = \begin{pmatrix} a \cos q_1 \\ a \sin q_1 \cos q_2 \\ \dots \\ a \sin q_1 \cdots \sin q_{n-2} \cos q_{n-1} \\ a \sin q_1 \cdots \sin q_{n-2} \sin q_{n-1} \end{pmatrix}.$$

4. Construction of a recursion op. for the geodesic flow on S^n - 2

① Considering the canonical Riemannian metric on S^n

Using the spherical polar coordinate for an n -dimensional sphere of radius a , we consider an embedding ϕ to the sphere:

$$\phi(q^1, \dots, q^n) = \begin{pmatrix} a \cos q_1 \\ a \sin q_1 \cos q_2 \\ \dots \\ a \sin q_1 \cdots \sin q_{n-2} \cos q_{n-1} \\ a \sin q_1 \cdots \sin q_{n-2} \sin q_{n-1} \end{pmatrix}.$$

We see that

$$g_{ij} = \rho_i^2 \delta_{ij}, \quad \left(i, j = 1, \dots, n, \rho_1 = a, \rho_\ell = a \prod_{k=1}^{\ell-1} \sin q_k, (\ell = 2, \dots, n) \right).$$

4. Construction of a recursion op. for the geodesic flow on S^n - 3

- ② Calculating the Hamiltonian H from the metric

4. Construction of a recursion op. for the geodesic flow on S^n - 3

② Calculating the Hamiltonian H from the metric

The corresponding Hamiltonian function H is

$$H(q, p) = \frac{1}{2a^2} \sum_{k=1}^n P_k \cdot p_k^2, \quad P_k = \begin{cases} 1, & (k = 1), \\ \prod_{i=1}^{k-1} \frac{1}{\sin^2 q_i}, & (\textit{otherwise}). \end{cases} \quad (1)$$

4. Construction of a recursion op. for the geodesic flow on S^n - 4

③ Describing the Hamiltonian system (H, Δ, ω) - 1

4. Construction of a recursion op. for the geodesic flow on S^n - 4

③ Describing the Hamiltonian system (H, Δ, ω) - 1

The Hamilton-Jacobi equation for (1) is

$$E = \frac{1}{2a^2} \sum_{k=1}^n P_k \left(\frac{dS_k}{dq_k} \right)^2, \quad S = \sum_{i=1}^n S_i(q_i),$$

where S is generating function.

4. Construction of a recursion op. for the geodesic flow on S^n - 5

③ Describing the Hamiltonian system (H, Δ, ω) - 2

4. Construction of a recursion op. for the geodesic flow on S^n - 5

③ Describing the Hamiltonian system (H, Δ, ω) - 2

By the variable transformation, we assume the following:

$$Q_\ell := \left\{ R_\ell - \left(\frac{dS_\ell}{dq_\ell} \right)^2 \right\} \sin^2 q_\ell = \sum_{k=1}^{n-\ell} P_k \left(\frac{dS_{\ell+k}}{dq_{\ell+k}} \right)^2,$$

where

$$R_\ell = \begin{cases} 2a^2 E, & (\ell = 1), \\ Q_{\ell-1}, & (\textit{otherwise}), \end{cases} \quad P_k = \begin{cases} 1, & (k = 1), \\ \prod_{i=\ell}^{\ell+k-2} \frac{1}{\sin^2 q_i}, & (\textit{otherwise}). \end{cases}$$

4. Construction of a recursion op. for the geodesic flow on S^n - 5

③ Describing the Hamiltonian system (H, Δ, ω) - 2

By the variable transformation, we assume the following:

$$Q_\ell := \left\{ R_\ell - \left(\frac{dS_\ell}{dq_\ell} \right)^2 \right\} \sin^2 q_\ell = \sum_{k=1}^{n-\ell} P_k \left(\frac{dS_{\ell+k}}{dq_{\ell+k}} \right)^2,$$

where

$$R_\ell = \begin{cases} 2a^2E, & (\ell = 1), \\ Q_{\ell-1}, & (\text{otherwise}), \end{cases} \quad P_k = \begin{cases} 1, & (k = 1), \\ \prod_{i=\ell}^{\ell+k-2} \frac{1}{\sin^2 q_i}, & (\text{otherwise}). \end{cases}$$

Q_ℓ, E and a are constants, so we can set $\alpha_1 := \sqrt{2a^2E}$ and $\alpha_\ell := \sqrt{Q_{\ell-1}}$, therefore,

$$p_\ell = \frac{dS_\ell}{dq_\ell} = \begin{cases} \sqrt{\alpha_\ell^2 - \frac{\alpha_{\ell+1}^2}{\sin^2 q_\ell}}, & (\ell = 1, \dots, n-1), \\ \alpha_\ell, & (\ell = n). \end{cases} \quad (2)$$

4. Construction of a recursion op. for the geodesic flow on S^n - 6

③ Describing the Hamiltonian system (H, Δ, ω) - 3

4. Construction of a recursion op. for the geodesic flow on S^n - 6

③ Describing the Hamiltonian system (H, Δ, ω) - 3

Then, let $J_\ell := \frac{1}{2\pi} \oint p_\ell dq_\ell$, we obtain the action variables $J_\ell(q, p)$:

$$J_\ell = \begin{cases} \alpha_\ell - \alpha_{\ell+1}, & (\ell = 1, \dots, n-1), \\ \alpha_n, & (\ell = n), \end{cases}$$

4. Construction of a recursion op. for the geodesic flow on S^n - 6

③ Describing the Hamiltonian system (H, Δ, ω) - 3

Then, let $J_\ell := \frac{1}{2\pi} \oint p_\ell dq_\ell$, we obtain the action variables $J_\ell(q, p)$:

$$J_\ell = \begin{cases} \alpha_\ell - \alpha_{\ell+1}, & (\ell = 1, \dots, n-1), \\ \alpha_n, & (\ell = n), \end{cases}$$

hence

$$\alpha_\ell = \sum_{k=\ell}^n J_k. \quad (3)$$

4. Construction of a recursion op. for the geodesic flow on S^n - 7

③ Describing the Hamiltonian system (H, Δ, ω) - 4

4. Construction of a recursion op. for the geodesic flow on S^n - 7

③ Describing the Hamiltonian system (H, Δ, ω) - 4

Therefore, from (1), (2) and (3), H is written as a function of J_i ,

$$H(J) = \frac{1}{2a^2} \left(\sum_{i=1}^n J_i \right)^2.$$

4. Construction of a recursion op. for the geodesic flow on S^n - 7

③ Describing the Hamiltonian system (H, Δ, ω) - 4

Therefore, from (1), (2) and (3), H is written as a function of J_i ,

$$H(J) = \frac{1}{2a^2} \left(\sum_{i=1}^n J_i \right)^2.$$

The corresponding Hamiltonian vector field Δ is

$$\Delta = \{H, \cdot\} = \frac{1}{a^2} \sum_{i,t=1}^n J_i \frac{\partial}{\partial \varphi_t}$$

4. Construction of a recursion op. for the geodesic flow on S^n - 7

③ Describing the Hamiltonian system (H, Δ, ω) - 4

Therefore, from (1), (2) and (3), H is written as a function of J_i ,

$$H(J) = \frac{1}{2a^2} \left(\sum_{i=1}^n J_i \right)^2.$$

The corresponding Hamiltonian vector field Δ is

$$\Delta = \{H, \cdot\} = \frac{1}{a^2} \sum_{i,t=1}^n J_i \frac{\partial}{\partial \varphi_t}$$

and the symplectic form ω is

$$\omega = \sum_{i=1}^n dJ_i \wedge d\varphi^i. \quad (4)$$

4. Construction of a recursion op. for the geodesic flow on S^n - 8

From the above,

4. Construction of a recursion op. for the geodesic flow on S^n - 8

From the above, the tensor field T defined by

$$T = \frac{1}{2} \sum_{i,\ell} \left\{ ({}^t\mathcal{S})^{\ell}_{\ i} \frac{\partial}{\partial J_i} \otimes dJ_{\ell} + \mathcal{S}^i_{\ \ell} \frac{\partial}{\partial \varphi^i} \otimes d\varphi^{\ell} \right\} \quad (5)$$

4. Construction of a recursion op. for the geodesic flow on S^n - 8

From the above, the tensor field T defined by

$$T = \frac{1}{2} \sum_{i,\ell} \left\{ ({}^t S)_i^\ell \frac{\partial}{\partial J_i} \otimes dJ_\ell + S_\ell^i \frac{\partial}{\partial \varphi^i} \otimes d\varphi^\ell \right\} \quad (5)$$

where

$$\begin{cases} S_1^1 = J_1, \\ S_1^i = -\sum_k J_k + J_1 + 2J_i, & (i > 2), \\ S_\ell^\ell = \sum_k J_k - J_\ell, & (\ell > 2), \\ S_\ell^i = J_\ell & (\textit{otherwise}) \end{cases} \quad (6)$$

4. Construction of a recursion op. for the geodesic flow on S^n - 8

From the above, the tensor field T defined by

$$T = \frac{1}{2} \sum_{i,\ell} \left\{ ({}^t S)^\ell_i \frac{\partial}{\partial J_i} \otimes dJ_\ell + S^i_\ell \frac{\partial}{\partial \varphi^i} \otimes d\varphi^\ell \right\} \quad (5)$$

where

$$\begin{cases} S^1_1 = J_1, \\ S^i_1 = -\sum_k J_k + J_1 + 2J_i, & (i > 2), \\ S^\ell_\ell = \sum_k J_k - J_\ell, & (\ell > 2), \\ S^i_\ell = J_\ell & (\textit{otherwise}) \end{cases} \quad (6)$$

fullfills the conditions for the recursion operator.

4. Construction of a recursion op. for the geodesic flow on S^n - 10

Thus, we obtained the following proposition from the above:

4. Construction of a recursion op. for the geodesic flow on S^n - 10

Thus, we obtained the following proposition from the above:

Proposition (HT)

When we introduced a canonical Riemannian metric g on S^n , the geodesic flow of T^*S^n has a recursion operator T . T is written by means of action-angle variables $(J(q, p), \varphi(q, p))$:

$$T = \frac{1}{2} \sum_{i, \ell} \left\{ ({}^t S)_i^\ell \frac{\partial}{\partial J_i} \otimes dJ_\ell + S_\ell^i \frac{\partial}{\partial \varphi_i} \otimes d\varphi_\ell \right\}$$

where (q, p) is a local coordinate system on T^*S^n .

4. Construction of a recursion op. for the geodesic flow on S^n - 10

Thus, we obtained the following proposition from the above:

Proposition (HT)

When we introduced a canonical Riemannian metric g on S^n , the geodesic flow of T^*S^n has a recursion operator T . T is written by means of action-angle variables $(J(q, p), \varphi(q, p))$:

$$T = \frac{1}{2} \sum_{i, \ell} \left\{ ({}^t S)_i^\ell \frac{\partial}{\partial J_i} \otimes dJ_\ell + S_\ell^i \frac{\partial}{\partial \varphi_i} \otimes d\varphi_\ell \right\}$$

where (q, p) is a local coordinate system on T^*S^n .

Example (3-dimensional case)

4. Construction of a recursion op. for the geodesic flow on S^n - 10

Thus, we obtained the following proposition from the above:

Proposition (HT)

When we introduced a canonical Riemannian metric g on S^n , the geodesic flow of T^*S^n has a recursion operator T . T is written by means of action-angle variables $(J(q, p), \varphi(q, p))$:

$$T = \frac{1}{2} \sum_{i,\ell} \left\{ ({}^tS)_i^\ell \frac{\partial}{\partial J_i} \otimes dJ_\ell + S_\ell^i \frac{\partial}{\partial \varphi_i} \otimes d\varphi_\ell \right\}$$

where (q, p) is a local coordinate system on T^*S^n .

Example (3-dimensional case)

$$T = \frac{1}{2} \begin{pmatrix} J_1 & J_2 - J_3 & J_3 - J_2 & & & & \mathbf{O} \\ J_2 & J_1 + J_3 & J_2 & & & & \\ J_3 & J_3 & J_1 + J_2 & & & & \\ \mathbf{O} & & & J_1 & J_2 & J_3 & \\ & & & J_2 - J_3 & J_1 + J_3 & J_3 & \\ & & & J_3 - J_2 & J_2 & J_1 + J_2 & \end{pmatrix}.$$

5. Application of the recursion operator for the geodesic flow on n -dimensional sphere

5. Application of a recursion operator for the geodesic flow on S^n - 1

Constants of the motion

5. Application of a recursion operator for the geodesic flow on $S^n - 1$

Constants of the motion

The constants of motion F_k of the geodesic flow is:

$$F_k = \text{Tr}(T^k) = 2 \sum_{i=1}^n \lambda_i^k, \quad (k = 1, \dots, n),$$

where λ_i are the eigenvalues of T .

5. Application of a recursion operator for the geodesic flow on $S^n - 1$

Constants of the motion

The constants of motion F_k of the geodesic flow is:

$$F_k = \text{Tr}(T^k) = 2 \sum_{i=1}^n \lambda_i^k, \quad (k = 1, \dots, n),$$

where λ_i are the eigenvalues of T .

Example (3-dimensional case)

5. Application of a recursion operator for the geodesic flow on $S^n - 1$

Constants of the motion

The constants of motion F_k of the geodesic flow is:

$$F_k = \text{Tr}(T^k) = 2 \sum_{i=1}^n \lambda_i^k, \quad (k = 1, \dots, n),$$

where λ_i are the eigenvalues of T .

Example (3-dimensional case)

$$\begin{cases} F_1 &= 3J_1 + J_2 + J_3 &= \lambda_1 + \lambda_2 + \lambda_3, \\ F_2 &= 3(J_1^2 + J_2^2 + J_3^2) + 2(J_1J_2 - J_2J_3 + J_3J_1) &= \lambda_1^2 + \lambda_2^2 + \lambda_3^2, \\ F_3 &= \dots\dots\dots &= \lambda_1^3 + \lambda_2^3 + \lambda_3^3. \end{cases}$$

5. Application of a recursion operator for the geodesic flow on $S^n - 1$

Constants of the motion

The constants of motion F_k of the geodesic flow is:

$$F_k = \text{Tr}(T^k) = 2 \sum_{i=1}^n \lambda_i^k, \quad (k = 1, \dots, n),$$

where λ_i are the eigenvalues of T .

Example (3-dimensional case)

$$\begin{cases} F_1 &= 3J_1 + J_2 + J_3 &= \lambda_1 + \lambda_2 + \lambda_3, \\ F_2 &= 3(J_1^2 + J_2^2 + J_3^2) + 2(J_1J_2 - J_2J_3 + J_3J_1) &= \lambda_1^2 + \lambda_2^2 + \lambda_3^2, \\ F_3 &= \dots\dots\dots &= \lambda_1^3 + \lambda_2^3 + \lambda_3^3. \end{cases}$$

Thus, the constants of motion are obtained by traces of the k th powers of T .

5. Application of a recursion operator for the geodesic flow on S^n - 2

The symplectic form ω_1 , which is induced by (5) and (6), is written as follows:

$$\omega_1 = \sum_{i,\ell} S^i_\ell dJ_i \wedge d\varphi^\ell.$$

5. Application of a recursion operator for the geodesic flow on $S^n - 2$

The symplectic form ω_1 , which is induced by (5) and (6), is written as follows:

$$\omega_1 = \sum_{i,\ell} S^i_{\ell} dJ_i \wedge d\varphi^{\ell}.$$

We get

$$dK_i = \sum_{k=1}^n ({}^t S)^i_k dJ_k, \quad \omega_1 = \sum_{i=1}^n dK_i \wedge d\alpha_i, \quad (\alpha_i = \varphi_i).$$

5. Application of a recursion operator for the geodesic flow on $S^n - 2$

The symplectic form ω_1 , which is induced by (5) and (6), is written as follows:

$$\omega_1 = \sum_{i,\ell} S^i_{\ell} dJ_i \wedge d\varphi^{\ell}.$$

We get

$$dK_i = \sum_{k=1}^n ({}^t S)^i_k dJ_k, \quad \omega_1 = \sum_{i=1}^n dK_i \wedge d\alpha_i, \quad (\alpha_i = \varphi_i).$$

The ω_1 can be considered as the Lie derivative of the symplectic form ω given by equation (4) with respect to the vector field

$$\Gamma = \sum_{i=1}^n K_i \frac{\partial}{\partial J_i},$$

5. Application of a recursion operator for the geodesic flow on $S^n - 2$

The symplectic form ω_1 , which is induced by (5) and (6), is written as follows:

$$\omega_1 = \sum_{i,\ell} S^i_{\ell} dJ_i \wedge d\varphi^{\ell}.$$

We get

$$dK_i = \sum_{k=1}^n ({}^t S)^i_k dJ_k, \quad \omega_1 = \sum_{i=1}^n dK_i \wedge d\alpha_i, \quad (\alpha_i = \varphi_i).$$

The ω_1 can be considered as the Lie derivative of the symplectic form ω given by equation (4) with respect to the vector field

$$\Gamma = \sum_{i=1}^n K_i \frac{\partial}{\partial J_i},$$

therefore,

$$\omega_1 = \mathcal{L}_{\Gamma} \omega.$$

5. Application of a recursion operator for the geodesic flow on S^n - 3

A sequence of Abelian symmetries (Γ -scheme[5])

5. Application of a recursion operator for the geodesic flow on S^n - 3

A sequence of Abelian symmetries (Γ -scheme[5])

We can set the new vector fields Δ_{i+1} as follows:

$$\Delta_{i+1} := [\Delta_i, \Gamma], \quad \Delta_0 = \Delta$$

5. Application of a recursion operator for the geodesic flow on S^n - 3

A sequence of Abelian symmetries (Γ -scheme[5])

We can set the new vector fields Δ_{i+1} as follows:

$$\Delta_{i+1} := [\Delta_i, \Gamma], \quad \Delta_0 = \Delta = \frac{J_1 + \cdots + J_n}{2a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right),$$

5. Application of a recursion operator for the geodesic flow on $S^n - 3$

A sequence of Abelian symmetries (Γ -scheme[5])

We can set the new vector fields Δ_{i+1} as follows:

$$\Delta_{i+1} := [\Delta_i, \Gamma], \quad \Delta_0 = \Delta = \frac{J_1 + \cdots + J_n}{2a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right),$$

so that

$$\Delta_{i+1} = (-1)^{i+1} \frac{(i+1)! (J_1 + \cdots + J_n)^{i+2}}{2^{i+1} a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right), \quad (i = 0, \dots, n-1).$$

5. Application of a recursion operator for the geodesic flow on $S^n - 3$

A sequence of Abelian symmetries (Γ -scheme[5])

We can set the new vector fields Δ_{i+1} as follows:

$$\Delta_{i+1} := [\Delta_i, \Gamma], \quad \Delta_0 = \Delta = \frac{J_1 + \cdots + J_n}{2a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right),$$

so that

$$\Delta_{i+1} = (-1)^{i+1} \frac{(i+1)! (J_1 + \cdots + J_n)^{i+2}}{2^{i+1} a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right), \quad (i = 0, \dots, n-1).$$

The generated Δ_i by the commutator are the Hamiltonian vector field which commute between them:

$$[\Delta_i, \Delta_\ell] = \mathbf{0},$$

5. Application of a recursion operator for the geodesic flow on $S^n - 3$

A sequence of Abelian symmetries (Γ -scheme[5])

We can set the new vector fields Δ_{i+1} as follows:

$$\Delta_{i+1} := [\Delta_i, \Gamma], \quad \Delta_0 = \Delta = \frac{J_1 + \cdots + J_n}{2a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right),$$

so that

$$\Delta_{i+1} = (-1)^{i+1} \frac{(i+1)! (J_1 + \cdots + J_n)^{i+2}}{2^{i+1} a^2} \left(\frac{\partial}{\partial \varphi_1} + \cdots + \frac{\partial}{\partial \varphi_n} \right), \quad (i = 0, \dots, n-1).$$

The generated Δ_i by the commutator are the Hamiltonian vector field which commute between them:

$$[\Delta_i, \Delta_\ell] = \mathbf{0},$$

and corresponding Hamiltonian function is

$$H_{i+1} = (-1)^{i+1} \frac{1}{(i+3) \cdot 2^{i+1} a^2} (J_1 + \cdots + J_n)^{i+3}.$$

5. Application of a recursion operator for the geodesic flow on S^n - 4

In general, from a recursion operator T , given by (5) and (6), the commutator generates a sequence of Abelian symmetries between each Δ_{i+1} *s.t.*

$$\Delta_{i+1} := [\Delta_i, \Gamma]. \quad (7)$$

5. Application of a recursion operator for the geodesic flow on S^n - 4

In general, from a recursion operator T , given by (5) and (6), the commutator generates a sequence of Abelian symmetries between each Δ_{i+1} *s.t.*

$$\Delta_{i+1} := [\Delta_i, \Gamma]. \quad (7)$$

Thus, we obtained the following proposition:

5. Application of a recursion operator for the geodesic flow on $S^n - 4$

In general, from a recursion operator T , given by (5) and (6), the commutator generates a sequence of Abelian symmetries between each Δ_{i+1} *s.t.*

$$\Delta_{i+1} := [\Delta_i, \Gamma]. \quad (7)$$

Thus, we obtained the following proposition:

Proposition (1)

*In the n -dimensional sphere case, there exists the sequence of Abelian symmetries, generated by (7), *s.t.**

$$\begin{cases} \Delta_0 = \Delta = \frac{J_1 + \dots + J_n}{2a^2} \left(\frac{\partial}{\partial \varphi_1} + \dots + \frac{\partial}{\partial \varphi_n} \right), \\ \Delta_{i+1} = (-1)^{i+1} \frac{(i+1)! (J_1 + \dots + J_n)^{i+2}}{2^{i+1} a^2} \left(\frac{\partial}{\partial \varphi_1} + \dots + \frac{\partial}{\partial \varphi_n} \right), (i = 0, \dots, n-1). \end{cases}$$

And, the corresponding Hamiltonian function is

$$H_{i+1} = (-1)^{i+1} \frac{1}{(i+3) \cdot 2^{i+1} a^2} (J_1 + \dots + J_n)^{i+3}.$$

6. Conclusion

6. Conclusion

☆ The geodesic flow on n -dimensional sphere has a recursion operator T .

6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.

6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.
- ★ Is there a T_1 ,

6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.
- ★ Is there a T_1 , likewise the case of the Minkowski metric?

6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.
- ★ Is there a T_1 , likewise the case of the Minkowski metric? If there is, $T_1 = T$ or $T_1 \neq T$?

6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.
- ★ Is there a T_1 , likewise the case of the Minkowski metric? If there is, $T_1 = T$ or $T_1 \neq T$? (WIP)






6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.
- ★ Is there a T_1 , likewise the case of the Minkowski metric? If there is, $T_1 = T$ or $T_1 \neq T$? (WIP)
- ★ How about on the other geometric structure?

6. Conclusion

- ☆ The geodesic flow on n -dimensional sphere has a recursion operator T .
- ☆ Using the properties of the T , we got a sequence of Abelian symmetric vector fields and a sequence of involutive Hamiltonian function.
- ★ Is there a T_1 , likewise the case of the Minkowski metric? If there is, $T_1 = T$ or $T_1 \neq T$? (WIP)
- ★ How about on the other geometric structure? (WIP)

References

-  V. I. Arnold, *Mathematical Methods of Classical Mechanics*, Springer-Verlag, 1989.
-  S. De Filippo, G. Marmo, M. Salerno, and G. Vilasi, A new characterization of completely integrable systems, *Il N. Cimento* B83, 97 (1984).
-  S. De Filippo, G. Marmo, and G. Vilasi, A geometrical setting for the Lax representation, *Phys. Lett.* B117(6), 418 (1982).
-  G. Marmo, G. Vilasi, When do recursion operators generate new conservation laws?, *Phys. Lett.* B277 (1992), no. 1-2, 137-140.
-  G. Vilasi, *Hamiltonian dynamics*, World Scientific Publishing Co., Inc., River Edge, NJ, 2001.

Thank you for your attention!